

Polynomial Preserving Diffusions on the Unit Ball

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joint work with Sergio Pulido

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Polynomial models in finance

Factor models

- ▶ Arbitrage-free pricing usually boils down to calculating conditional expectations:

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- ▶ **Task:** Find X and f to get **tractable yet flexible** class of models

Polynomial preserving diffusions

- ▶ Markov process X with state space $E \subseteq \mathbb{R}^d$
- ▶ (Extended) generator \mathcal{G} given by

$$\mathcal{G}f(x) = b(x)^\top \nabla f(x) + \frac{1}{2} \text{Tr}(a(x) \nabla^2 f(x))$$

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Definition. X is called **Polynomial Preserving (PP)** if

$$\mathcal{G} \text{Pol}_n(E) \subseteq \text{Pol}_n(E) \quad \text{for all } n \in \mathbb{N},$$

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Lemma. X is (PP) if and only if

$$b_i \in \text{Pol}_1(E) \quad \text{and} \quad a_{ij} \in \text{Pol}_2(E)$$

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- ▶ Coordinate representations:

$$\begin{aligned} p(x) &= H(x)^{\top} \vec{p} & \vec{p} &\in \mathbb{R}^N \\ \mathcal{G}p(x) &= H(x)^{\top} G \vec{p} & G &\in \mathbb{R}^{N \times N} \end{aligned}$$

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$$\begin{aligned} \mathbb{E}[p(X_T) \mid \mathcal{F}_t] &= e^{(T-t)\mathcal{G}} p(X_t) && \text{(formally)} \\ &= H(X_t)^{\top} e^{(T-t)G} \vec{p} \end{aligned}$$

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- ▶ This only involves a **matrix exponential** as opposed to solving a PDE which leads to tractable pricing models

Polynomial preserving diffusions

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- ▶ Pearson diffusions (Forman and Sørensen, 2008), $E \subset \mathbb{R}$:

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More generally:

- ▶ Existence theory for polynomial preserving diffusions is available when E is a **basic closed semialgebraic set**:

$$E = \{x \in \mathbb{R}^d : p_1(x) \geq 0, \dots, p_m(x) \geq 0\}$$

where $p_1, \dots, p_m \in \text{Pol}(\mathbb{R}^d)$. See Filipović & L. (2014).

Literature

- ▶ Wong (1964)
- ▶ Mazet (1997)
- ▶ Zhou (2003)
- ▶ Forman and Sørensen (2008)
- ▶ Cuchiero, Keller-Ressel, Teichmann (2012)
- ▶ Filipović, Gourier, Mancini (2013)
- ▶ Filipović, L. (2014)
- ▶ Bakry, Orevkov, Zani (2014)
- ▶ Filipović, L., Trolle (2014)
- ▶ ...

(PP) diffusions on the unit ball

The role of the state space

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Example. Affine diffusions on $E = \mathbb{R}_+^d$:

$$dX_t = (b + BX_t)dt + \begin{pmatrix} \sigma_1\sqrt{X_{1t}} & 0 & \cdots & 0 \\ 0 & \sigma_2\sqrt{X_{2t}} & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & \cdots & 0 & \sigma_d\sqrt{X_{dt}} \end{pmatrix} dW_t$$

Geometry of E forces $\langle X_i, X_j \rangle \equiv 0$ for $i \neq j$.

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- ▶ Compact state spaces useful for polynomial approximation

Theorem. If E is compact and X is an E -valued affine diffusion, then X is **deterministic**.

PP diffusions on the unit ball

Example.

$$dX_t = -X_t dt + \sqrt{1 - \|X_t\|^2} dW_t$$

where $W = (W^1, \dots, W^d)$ is d -dimensional BM.

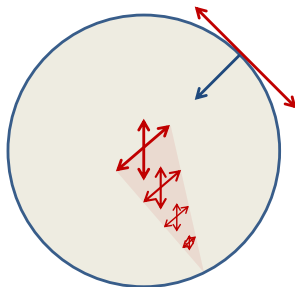
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But richer diffusion dynamics is possible:



PP diffusions on the unit ball

Theorem. X is a PP diffusion on the unit ball if and only if

$$b(x) = b + Bx \quad \text{and} \quad a(x) = (1 - \|x\|^2)\alpha + c(x)$$

for some $b \in \mathbb{R}^d$, $B \in \mathbb{R}^{d \times d}$, $\alpha \in \mathbb{S}_+^d$, and $c \in \mathcal{C}_+$ such that

$$b^\top x + x^\top Bx + \frac{1}{2} \text{Tr}(c(x)) \leq 0 \quad \text{for all } x \in \mathcal{S}^{d-1}.$$

Here \mathcal{S}^{d-1} is the unit sphere in \mathbb{R}^d , and

$$\mathcal{C}_+ = \left\{ c : \mathbb{R}^d \rightarrow \mathbb{S}^d : \begin{array}{l} c_{ij} \in \text{Hom}_2 \text{ for all } i, j \\ c(x)x \equiv 0 \\ c(x) \in \mathbb{S}_+^d \text{ for all } x \end{array} \right\}$$

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Examples of $c \in \mathcal{C}_+$:

- ▶ Take $A_1 \in \text{Skew}(d)$ and set

$$c(x) = A_1 x x^\top A_1^\top$$

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- ▶ Take $A_1, \dots, A_m \in \text{Skew}(d)$ and set

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- ▶ ... but is this exhaustive?

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| $c(x) = \sum_{p=1}^m A_p x x^\top A_p^\top$ | \iff | $\text{BQ}(x, y) = \sum_p (y^\top A_p x)^2$
= sum of squares (SOS) |

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= sum of squares (**SOS**)

$\mathcal{C}_+ \cong \{\text{all nonnegative biquadratic forms with vanishing diagonal}\}$
 $\stackrel{?}{=} \{\text{all **SOS** biquadratic forms with vanishing diagonal}\}$

Nonnegativity vs. sum of squares

- ▶ **Hilbert (1888)**: Every nonnegative homogeneous polynomial of degree k in d variables is **SOS** if and only if

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- ▶ **Quarez (2010)** on biquadratic forms:
 - ▶ Every nonnegative biquadratic form in $3 + 3$ variables with at least 11 zeros is **SOS**
 - ▶ There exist nonnegative biquadratic forms in $4 + 4$ variables with infinitely many zeros that are not **SOS**

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- ▶ **László (2010)**: There exist nonnegative, non-**SOS** biquadratic forms with vanishing diagonal in $6 + 6$ variables.

Nonnegativity vs. sum of squares

Theorem.

- (i) If $d \leq 4$, then any nonnegative biquadratic form in $d + d$ variables vanishing on the diagonal is **SOS**. Equivalently, any $c \in \mathcal{C}_+$ is of the form

$$c(x) = \sum_{p=1}^m A_p x x^\top A_p^\top \quad \text{for some} \quad A_1, \dots, A_m \in \text{Skew}(d).$$

- (ii) If $d \geq 6$, then there exist nonnegative biquadratic forms in $d + d$ variables vanishing on the diagonal that is not **SOS**. Equivalently, there exist $c \in \mathcal{C}_+$ that is not of the above form.

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Open question: What happens for $d = 5$?

Nonnegativity vs. sum of squares

Example. Let $d = 6$. The map $c : \mathbb{R}^d \rightarrow \mathbb{S}^d$ with components

$$c_{11} = (x_2 + x_3 + x_4 + x_5 + x_6)^2$$

$$c_{12} = (x_2 + x_3 + x_4 + x_5 + x_6)(-x_1 + x_3 + x_4 + x_5 + x_6)$$

$$c_{13} = (x_2 + x_3 + x_4 + x_5 + x_6)(-x_1 - x_2 + x_4 + x_5 + x_6)$$

$$c_{14} = (x_2 + x_3 + x_4 + x_5 + x_6)(-x_1 - x_2 - x_3 + x_5 + x_6)$$

$$c_{15} = (x_2 + x_3 + x_4 + x_5 + x_6)(-x_1 - x_2 - x_3 - x_4 + x_6)$$

$$c_{16} = (x_2 + x_3 + x_4 + x_5 + x_6)(-x_1 - x_2 - x_3 - x_4 - x_5)$$

$$c_{22} = (x_1 - x_3 - x_4 - x_5 - x_6)^2$$

$$c_{23} = (x_1 - x_3 - x_4 - x_5 - x_6)(x_1 + x_2 - x_4 - x_5 - x_6)$$

$$c_{24} = (x_1 - x_3 - x_4 - x_5 - x_6)(x_1 + x_2 + x_3 - x_5 - x_6)$$

$$c_{25} = (x_1 - x_3 - x_4 - x_5 - x_6)(x_1 + x_2 + x_3 + x_4 - x_6)$$

$$c_{26} = (x_1 - x_3 - x_4 - x_5 - x_6)(x_1 + x_2 + x_3 + x_4 + x_5)$$

$$c_{33} = (x_1 + x_2 - x_4 - x_5 - x_6)^2$$

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$$c_{36} = (x_1 + x_2 - x_4 - x_5 - x_6)(x_1 + x_2 + x_3 + x_4 + x_5)$$

$$c_{44} = (x_1 + x_2 + x_3 - x_5 - x_6)^2$$

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$$c_{46} = (x_1 + x_2 + x_3 - x_5 - x_6)(x_1 + x_2 + x_3 + x_4 + x_5)$$

$$c_{55} = (x_1 + x_2 + x_3 + x_4 - x_6)^2$$

$$c_{56} = (x_1 + x_2 + x_3 + x_4 - x_6)(x_1 + x_2 + x_3 + x_4 + x_5)$$

$$c_{66} = (x_1 + x_2 + x_3 + x_4 + x_5)^2$$

lies in \mathcal{C}_+ but $y^\top c(x)y$ is **not SOS**.

Consequences of **SOS**: PP diffusions on the unit sphere

- ▶ Let X be PP diffusion on $\mathcal{S}^{d-1} = \{x \in \mathbb{R}^d : \|x\| = 1\}$

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- ▶ Such X are characterized by

$$\mathcal{L}f(x) = (Bx)^\top \nabla f(x) + \frac{1}{2} \text{Tr}(c(x) \nabla^2 f(x))$$

with $c \in \mathcal{C}_+$ and $2x^\top Bx + \text{Tr}(c(x)) \equiv 0$.

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- ▶ \mathcal{S}^{d-1} is an interesting state space for applications:
 - ▶ It is **compact**: polynomial approximation works well
 - ▶ It has **no boundary**: simulation works well
 - ▶ Let $\mathbf{Z}_t = [X_t^{(1)} \ \dots \ X_t^{(n)}]$ be valued in $(\mathcal{S}^{d-1})^n$, $n \geq d$. Then

$$\mathbf{C}_t = \mathbf{Z}_t^\top \mathbf{Z}_t$$

is an $n \times n$ **correlation matrix** of rank at most d .

Consequences of **SOS**: PP diffusions on the unit sphere

Theorem. Let X be a PP diffusion on \mathcal{S}^{d-1} . Equivalent are:

- ▶ $y^\top c(x)y$ is **SOS**.
- ▶ X can be realized as the unique strong solution to the SDE

$$dX_t = (\circ dY_t) X_t,$$

where Y is correlated Brownian motion with drift on $\text{Skew}(d)$:

$$Y_t = A_0 t + A_1 W_t^1 + \cdots + A_m W_t^m$$

with $A_0, \dots, A_m \in \text{Skew}(d)$ and m -dim BM (W^1, \dots, W^m) .

- ▶ \mathcal{G} can be expressed in Hörmander form as

$$\mathcal{G} = V_0 + \frac{1}{2} \sum_{p=1}^m V_p^2,$$

where V_p is the linear vector field $V_p(x) = A_p x$, $A_p \in \text{Skew}(d)$.

Consequences of **SOS**: PP diffusions on the unit sphere

Corollary (existence of density). Let X be a PP diffusion on \mathcal{S}^{d-1} such that $y^\top c(x)y$ is **SOS**. The following are equivalent:

- (i) X_t ($t > 0$) has a smooth density w.r.t. area measure on \mathcal{S}^{d-1}
- (ii) $\text{Lie}\{A_1, \dots, A_m\} = \text{Skew}(d)$

Conclusion

- ▶ (PP) processes can be used to build flexible and tractable models
- ▶ Geometry of the state space crucially affects factor dynamics
- ▶ The unit ball is an interesting example of a compact state space allowing for rich factor dynamics
- ▶ (PP) diffusions with the SOS property ...
 - ▶ ... can be completely parameterized
 - ▶ ... can be represented as strong solutions to SDE
 - ▶ ... admit simple conditions for existence of smooth density

Thank you!