

Optimal Investment and Consumption with Small Transaction Costs

Johannes Muhle-Karbe

ETH Zürich and Swiss Finance Institute
Based on joint works with Jan Kallsen and Martin Herdegen

Imperial College, March 5, 2015

Introduction

Outline

Introduction

Results

Summary

Derivations

Introduction

Portfolio Choice with Frictions

- ▶ Optimal portfolio selection is a key problem in finance.
 - ▶ Individual decision making.
 - ▶ Starting point for equilibrium models.
- ▶ Frictionless theory after Merton (1969, 1973) prescribes incessant rebalancing.
 - ▶ Not feasible with *frictions*.
- ▶ Optimal behavior should reflect tradeoff between:
 - ▶ Displacement from optimal allocation.
 - ▶ Costs of trading.
- ▶ Important?
- ▶ When and how?
- ▶ Simple and robust adjustments?

Introduction

Passive Investment

- ▶ This talk: *proportional* costs. Bid-ask spreads.
- ▶ Key insight (Magill/Constantinides, 1976):
 - ▶ *No-trade region* around the frictionless target.
 - ▶ Remain inactive while inside.
 - ▶ Start trading when boundaries are breached.
- ▶ Mathematically precise formulation?
 - ▶ Davis/Norman (1990). Shreve/Soner (1994).
 - ▶ Singular control. Reflected diffusions à la Harrison.
- ▶ Numerical results (Constantinides, 1986):
 - ▶ Even small costs have large effect on asset demand.
 - ▶ But welfare loss is small if trading is reduced optimally.
- ▶ Assumes constant investment opportunities.
 - ▶ Strategies almost passive. Rebalancing is only motive to trade.
 - ▶ What about more active trading strategies?

Introduction

Active Investment

- ▶ Complex models typically intractable with frictions.
- ▶ Numerical results in concrete settings:
 - ▶ Lynch/Tan (2011). Backward induction.
 - ▶ Dai, Li, Liu, Wang (2014). Coupled PDEs.
 - ▶ Frictions have much bigger effect.
 - ▶ But difficult to understand structure and comparative statics.
- ▶ Alternative: *asymptotics* for small costs.
 - ▶ Treat problem as perturbation of its frictionless counterpart.
 - ▶ Compute leading-order corrections of optimal policy and performance.
 - ▶ Constant investment opportunities: Shreve/Soner (1994).
Janeček/Shreve (2004).
- ▶ Recent progress for active investment strategies..

Introduction

Active Investment ct'd

- ▶ Hedge a call option in Black-Scholes framework.
 - ▶ Whalley/Wilmott (1997). Almgren/Li (2011). Bichuch (2014).
- ▶ Maximize sum of one-period mean variance profits.
 - ▶ Mean-reversion strategies: Martin/Schöneborn (2011).
 - ▶ Trend following: Martin (2012). Bouchaud et al. (2012). Garleanu/Pedersen (2013). Collin-Dufresne et al. (2014).
- ▶ Infinite horizon investment/consumption problems.
 - ▶ Soner/Touzi (2013). Possamaï, Soner, Touzi (2014).
- ▶ Different concrete models and objectives.
- ▶ This talk: pass to *general* setting.
 - ▶ Uncovers underlying general structure.
 - ▶ Resulting formulas are easy to interpret and implement.
Robust with respect to particular model specifications.

Results

Model

General asset prices:

- ▶ One safe asset. Normalized to one.
- ▶ One risky asset. Traded with proportional costs $\varepsilon_t = \varepsilon \mathcal{E}_t > 0$.

Mid price:

$$dS_t = b_t^S dt + \sqrt{c_t^S} dW_t$$

- ▶ General diffusive dynamics.
- ▶ Can include heteroskedasticity and predictable returns leading to market timing.
- ▶ No Markovian structure required.
- ▶ Transaction costs can be random and time-varying. Itô process \mathcal{E}_t rescaled by small parameter ε .

Results

Model

General investment/consumption problem:

- ▶ Investor solves:

$$E \left[\int_0^T u_1(t, \kappa_t^\varepsilon) dt + u_2(X_T^\varepsilon(\varphi^\varepsilon, \kappa^\varepsilon)) \right] \rightarrow \max!$$

over policies $(\varphi_t^\varepsilon, \kappa_t^\varepsilon)$ with wealth processes

$$X_t^\varepsilon(\varphi^\varepsilon, \kappa^\varepsilon) = X_0 + \int_0^t \varphi_s^\varepsilon dS_s - \int_0^t \kappa_s^\varepsilon ds + \Psi_t - \int_0^t \varepsilon_s d\|\varphi^\varepsilon\|_s$$

- ▶ Utility from intermediate consumption and terminal wealth.
Random endowment stream Ψ_t .
- ▶ Covers hedging, lifecycle investing, market timing, etc.

Results

Approximately Optimal Policy

Adjustment of the frictionless optimal policy (Kallsen/M-K, 2014):

- ▶ Use frictionless consumption.
 - ▶ Robust. Only adjust for reduced wealth.
- ▶ Time- and state-dependent no-trade region:

$$[\overline{NT}_t - \Delta NT_t, \overline{NT}_t + \Delta NT_t]$$

- ▶ Midpoint \overline{NT}_t is frictionless target.
 - ▶ Also only adjusted for reduced wealth.
- ▶ Half-width ΔNT_t is the crucial quantity:

$$\Delta NT_t = \left(\frac{3R_t}{2} \frac{d\langle \varphi \rangle_t}{d\langle S \rangle_t} \varepsilon_t \right)^{1/3}$$

Results

Approximately Optimal Policy ct'd

- ▶ Half-width of optimal no-trade region:

$$\left(\frac{3R_t}{2} \frac{d\langle\varphi\rangle_t}{d\langle S\rangle_t} \varepsilon_t \right)^{1/3}$$

- ▶ Key driver: *portfolio gamma* $d\langle\varphi\rangle_t/d\langle S\rangle_t$.
 - ▶ Ratio of squared diffusion coefficients.
 - ▶ Active strategies require wide buffer.
 - ▶ Turbulent markets call for close tracking.
 - ▶ For delta-hedge: option gamma.
 - ▶ Sample from realized variance of frictionless benchmark.
- ▶ Only current spread ε_t matters for correction.
 - ▶ Future dynamics not hedged at the leading order.
- ▶ Preferences subsumed by *indirect risk-tolerance* R_t .

Results

Indirect Risk-Tolerance Process

Measure for risk tolerance?

- ▶ Risk tolerance $R_t = -\frac{U'(t, X_t)}{U''(t, X_t)}$ of the *indirect* utility:

$$U(t, x) = \sup_{(\varphi, \kappa)} E_t \left[\int_t^T u_1(s, \kappa_s) ds + u_2 \left(x + \int_t^T \varphi_s dS_s - \int_t^T \kappa_s ds \right) \right]$$

- ▶ Current against future consumption. Average over scenarios.
- ▶ Quantifies wealth-dependence of preferences.
- ▶ Bound to appear in *any* perturbation of frictionless problems.
 - ▶ Utility-based prices and hedges for small claims (Kramkov/Sîrbu, 2006).
 - ▶ Sensitivity of optimal consumption streams w.r.t. perturbations of the endowment (Herdegen/M-K, 2015).
- ▶ Here: novel *dynamic* characterization by quadratic BSDE.

Results

Performance

- ▶ Performance loss due to trading costs?
- ▶ Maximal utilities: $U(x)$ without and $U^\varepsilon(x)$ with costs.
- ▶ Certainty equivalent loss (Kallsen/M-K, 2014):

$$U^\varepsilon(x) \sim U \left(x - E^Q \left[\int_0^T \frac{(\Delta N T_t)^2}{2R_t} d\langle S \rangle_t \right] \right)$$

- ▶ Portfolio gamma $d\langle \varphi \rangle_t / d\langle S \rangle_t$ quantifies liquidity risk. Appealingly robust proxy: also central for..
 - ▶ ..discrete trading (Bertsimas, Kogan, Lo, 2000; Hayashi/Mykland, 2005)
 - ▶ ..optimal discretization (Fukasawa, 2011, 2013; Rosenbaum/Tankov, 2014)
 - ▶ ..other trading costs (Altarovici, M-K, Soner, 2013; Moreau, M-K, Soner, 2014)

Results

Performance ct'd

Performance loss:

- ▶ Portfolio gamma $d\langle\varphi\rangle_t/d\langle S\rangle_t$ determines magnitude.
 - ▶ Transaction costs matter for *active* trading!
- ▶ *Universal* scaling for welfare effect of small costs:
 - ▶ Two thirds caused by trading costs.
 - ▶ One third by displacement.
- ▶ For small transaction *tax* in the spirit of Tobin:
 - ▶ Two thirds of welfare loss paid to government.
Can be redistributed.
 - ▶ One third dissipates. True “friction”.
- ▶ Result surprisingly robust. Independent of asset price and cost dynamics, preferences, endowments.
- ▶ Only assumptions: diffusive prices, proportional cost structure.

Results

General Equilibrium

So far: partial equilibrium models. General equilibrium?

- ▶ Needed to analyze policies like a financial transaction tax.
 - ▶ 2/3-1/3 split of welfare losses robust?
- ▶ Finance literature: numerical solution of discrete models.
 - ▶ Buss/Dumas (2013). Buss, Uppal, Vilkov (2013).
- ▶ Only exception: Lo, Mamaysky, Wang (2004).
 - ▶ Asymptotic analysis of a particular model with fixed costs.
 - ▶ Bank account exogenous. No full equilibrium.
- ▶ Current work in progress with Martin Herdegen:
 - ▶ Endogenous asset returns and interest rates.
 - ▶ Two agents. Receive endowments. Invest and consume optimally in frictionless equilibrium.
 - ▶ Linear transaction tax paid to state. Consumes optimally.

Results

General Equilibrium ct'd

Effect of a *small* friction?

- ▶ Assume all agents use leading-order optimal strategies.
- ▶ No-trade regions have to match for stock market clearing:
 - ▶ Midpoints offset for exponential utilities.
 - ▶ Also need $\left(\frac{3R_t^1}{2} \frac{d\langle\varphi^1\rangle_t}{d\langle S\rangle_t} \varepsilon_t^1\right)^{1/3} = \left(\frac{3R_t^2}{2} \frac{d\langle\varphi^2\rangle_t}{d\langle S\rangle_t} \varepsilon_t^2\right)^{1/3}$
 - ▶ Frictionless market clearing implies $d\langle\varphi^1\rangle_t = d\langle\varphi^2\rangle_t$.
 - ▶ Split of tax $\varepsilon = \varepsilon_t^1 + \varepsilon_t^2$ determined by risk tolerances R_t^1, R_t^2 .
- ▶ Consumptions of agents and state need to clear bond market.
 - ▶ Can be ensured using sensitivity analysis of optimal consumption streams (Herdegen/M-K, 2015).
- ▶ Final result: frictionless equilibrium robust.
 - ▶ Does not need to change because of small friction.
 - ▶ Partial equilibrium analysis justified for exponential utilities.

Summary

Summary

- ▶ Approximately optimal policy with small proportional transaction costs.
 - ▶ “Myopic” correction for small frictions.
 - ▶ Drivers: current trading cost, indirect risk tolerance, portfolio gamma.
- ▶ Leading order welfare loss.
 - ▶ 2/3 due to trading costs, 1/3 due to displacement.
 - ▶ Portfolio gamma $d\langle\varphi\rangle_t/d\langle S\rangle_t$ quantifies liquidity risk.
- ▶ Results are very robust.
 - ▶ General preferences, price and cost dynamics.
 - ▶ Random endowments.
 - ▶ No Markovian structure required.
 - ▶ Results extend to other optimization criteria and frictions.
 - ▶ Extension to general equilibrium for exponential utilities.

Derivations

Small-Cost Expansion

- ▶ How to derive the results summarized above?
 - ▶ General, non-Markovian, singular control problem.
 - ▶ Where do the myopic small-cost corrections come from?
- ▶ Let us sketch the idea on an informal level.
- ▶ For simplicity:
 - ▶ Utility from terminal wealth only.
 - ▶ Constant absolute risk tolerance $R = -u'_2/u''_2$.
- ▶ Perform second-order Taylor expansion around the frictionless optimal wealth process $x + \int_0^T \varphi_t dS_t$.
- ▶ Two perturbations:
 - ▶ Small trading cost ε_t .
 - ▶ Small adjustment $\Delta\varphi_t$ of the trading strategy.

Derivations

Transaction Costs and Displacement

$$\begin{aligned} & E \left[u_2 \left(x + \int_0^T (\varphi_t + \Delta\varphi_t) dS_t - \int_0^T \varepsilon_t d\|\varphi + \Delta\varphi\|_t \right) \right] \\ & \approx E \left[u_2 \left(x + \int_0^T \varphi_t dS_t \right) \right] \\ & \quad + \beta E_Q \left[\int_0^T \Delta\varphi_t dS_t - \int_0^T \varepsilon_t d\|\varphi + \Delta\varphi\|_t \right] \\ & \quad - \frac{1}{2} \beta E_Q \left[R^{-1} \left(\int_0^T \Delta\varphi_t dS_t - \int_0^T \varepsilon_t d\|\varphi + \Delta\varphi\|_t \right)^2 \right] \end{aligned}$$

- Here: Q is the frictionless dual *martingale* measure with density $dQ/dP = u'_2(x + \int_0^T \varphi_t dS_t)/\beta$.

Derivations

Transaction Costs and Displacement ct'd

- ▶ Whence:

$$\begin{aligned} & E \left[u_2 \left(x + \int_0^T (\varphi_t + \Delta\varphi_t) dS_t - \int_0^T \varepsilon_t d\|\varphi + \Delta\varphi\|_t \right) \right] \\ & \approx E \left[u_2 \left(x + \int_0^T \varphi_t dS_t \right) \right] - \beta E_Q \left[\int_0^T \varepsilon_t d\|\varphi + \Delta\varphi\|_t \right] \\ & \quad - \frac{1}{2} \beta E_Q \left[R^{-1} \int_0^T (\Delta\varphi_t)^2 d\langle S \rangle_t \right] \end{aligned}$$

- ▶ First correction term represents expected transaction cost loss.
- ▶ Second corresponds to displacement loss.
- ▶ Computation?

Derivations

Homogenization

- ▶ Ansatz: optimal strategy remains close to frictionless target by reflection off trading boundaries.
- ▶ Whence: deviation follows reflected diffusion.
- ▶ Change of time, space: approximate by reflected Brownian motion with infinitesimal variance $d\langle\varphi\rangle_t/dt$ at the first order.
- ▶ Transaction costs = local time at boundaries.
 - ▶ Expectation given by $(d\langle\varphi\rangle_t/dt)/2\Delta NT_t$.
- ▶ Stationary law uniform.
 - ▶ Ergodic theorem allows to replace squared deviation $\Delta\varphi_t^2$ by expectation $\Delta NT^2/3$.
- ▶ Separation of time scales. Fast variable is “homogenized” out.

Derivations

Pointwise Optimization

In summary:

- ▶ Transaction cost loss:

$$\beta E_Q \left[\int_0^T \varepsilon_t \frac{d\langle \varphi \rangle_t / dt}{2\Delta NT_t} dt \right]$$

- ▶ Displacement loss:

$$\frac{\beta}{3R} E_Q \left[\int_0^T \Delta NT_t^2 \frac{d\langle S \rangle_t}{dt} dt \right]$$

- ▶ Optimal boundaries determined by *pointwise* maximization:

$$\Delta NT_t = \left(\frac{3R}{2} \frac{d\langle \varphi \rangle_t}{d\langle S \rangle_t} \varepsilon_t \right)^{1/3}$$

Derivations

Other frictions

Other trading costs? (\rightsquigarrow tonight's talk)

- ▶ Basic idea similar. But renormalized deviations differ:
 - ▶ Reflected Brownian motion for proportional costs.
 - ▶ Fixed costs: killed Brownian motion restarted at the origin.
 - ▶ OU-type process with quadratic costs.
- ▶ Trading costs scale differently.
- ▶ Asymptotic stationary law depends on control used:
 - ▶ Uniform for proportional costs.
 - ▶ “Hat function” for fixed costs.
 - ▶ Gaussian for quadratic costs.

For papers and preprints:

- ▶ <http://www.math.ethz.ch/~jmuhleka/>